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Receiver

[DOCUMENTATION FOR 1.12.0](#)

Please read receiver chapter of the documentation. Configure serial port (if required), receiver mode (serial/pwm/pwm), provider (for serial receivers), bind receiver, set channel map, configure channel endpoints/range on TX so that all channels go from ~1000 to ~2000. Set midpoint (default 1500), trim channels to 1500, configure stick deadband, verify behaviour when TX is off or out of range.
IMPORTANT: Before flying read failsafe chapter of documentation and configure failsafe.

Channel Map	RSSI Channel
AETR1234	Disabled
Roll	1512
Pitch	1513
Yaw	1505
Throttle	972
AUX 1	1454
AUX 2	1525
AUX 3	1500
AUX 4	1500
AUX 5	1500
AUX 6	1500
AUX 7	1500
AUX 8	1500



Throttle MID	Throttle EXPO
0.50	0.00

RC Deadband	Yaw Deadband
0	0



RC Rate	RC Expo
0.90	0.65

RC Yaw Expo
0.00

Refresh Save