

GyroAccelMagBaroGPSSerial

No dataflash chip found

Profile 1

Disconnect

2016-03-26 @ 21:23:20 -- Unique device ID received - 0x670ff575751777167244953

Show Log

Setup

Ports

Configuration

Failsafe

PID Tuning

Receiver

Modes

Adjustments

Servos

GPS

Motors

Race Transponder

LED Strip

Sensors

Tethered Logging

Blackbox

Use ranges to define the switches on your transmitter and corresponding mode assignments. A receiver channel that gives a reading between a range min/max will activate the mode. Remember to save your settings using the Save button.

ARM

Add Range

ANGLE

AUX 1

Min: 1300

Max: 1550

90010001200140015001600180020002100

Add Range

HORIZON

AUX 1

Min: 1600

Max: 1850

90010001200140015001600180020002100

Add Range

BARO

Add Range

AIR MODE

Add Range

Save

Port utilization: D: 5% U: 1%

Packet error: 0

I2C error: 0

Cycle Time: 1000

1.2.1

DE 21:36 26.03.2016